



GEFÖRDERT VOM



Bundesministerium für Bildung und Forschung

Investigating signal fluctuations of the surface detector array of the Pierre Auger Observatory using pair tanks

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Lateral Distribution Function (LDF)

Lateral particle density of EAS described by LDF:



(Auger Offline v2r4p1, Nucl. Inst. Meth. A 2006)

SD signal fluctuations

 Measured by pair tanks (distance: 11 m)
signal measured in units of VEM (Vertical Equivalent Muon)

28 pairs (7 triplets)

Number of particles in SD tank:
Poissonian statistics (sampling fluctuations)

Relative signal deviation:

$$\frac{\Delta S}{\overline{S}} := \sqrt{2} \cdot \frac{S_1 - S_2}{S_1 + S_2}$$

Other sources of signal fluctuations:

- fluctuations inside tank
- muon track length (zenith angle)
- LDF effect
- azimuthal effect



Reference: www.auger.org



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Relative signal fluctuations

- Relative signal fluctuation: RMS of $\frac{\Delta S}{\overline{S}}$ distribution
- Dividing signal range of pair samples into logarithmic bins
- 3 VEM threshold cut: avoid bias due to different trigger thresholds
- For low signals: apparent decrease of signal fluctuations



Poissonian-like behavior:



Fit results:

 $p_{\sigma} = 0.903 \pm 0.013$ (no noise constant) $p_{\sigma} = 0.934 \pm 0.008$ $p_{N} = 0.034 \pm 0.004$ (with noise constant)

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Threshold effect

 Poissonian model cannot follow threshold clipping
correction via Toy MC
Better: Analytical model

Probability that one tank is below threshold:

$$P(\overline{S} < S_{th}) = \frac{1}{\sqrt{2\pi p_{\sigma}^2 \overline{S}}} \int_{-\infty}^{S_{th}} \exp\left(-\frac{(x - \overline{S})^2}{2 p_{\sigma}^2 \overline{S}}\right) dx$$

Probability that the sample remains:

 $\overline{P}(\overline{S}$, $p_{\sigma}) \!=\! 1 \!-\! 2 P(\overline{S} \!<\! S_{th})$

Improved Poissonian model:

$$\left(\frac{\sigma}{\overline{S}}\right)^2 = \overline{P}(\overline{S}, p_{\sigma}) \frac{p_{\sigma}^2}{\overline{S}} (+p_N^2)$$

Fit results:

 $p_{\sigma} = 0.952 \pm 0.007$ (no noise constant) $p_{\sigma} = 0.933 \pm 0.007$ (with noise constant) $p_{N} = 0.037 \pm 0.004$





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Zenith angle dependency



 $\sigma = [(0.32 \pm 0.09) + (0.42 \pm 0.07) \sec \theta] \cdot \sqrt{\overline{S}}$





Impact onto energy estimation I

- LDF fit: Weighting of signals with their uncertainties
- Compare impact of official parameters

 $\sigma = [(0.32 \pm 0.09) + (0.42 \pm 0.07) \sec \theta] \cdot \sqrt{S}$

with that of the new ones

$$\sigma = [(0.32 \pm 0.04) + (0.47 \pm 0.03) \sec \theta] \cdot \sqrt{S}$$

Mean energy deviation:



RMS:

Impact onto energy estimation II

- How will estimated energy change when shifting all signals $\pm 1 \sigma$?
- Minus case: intercept negative signals set signal to zero

Mean energy deviation (minus case)

$$\left\langle \frac{\Delta E}{E} \right\rangle = (-16.1 \pm 0.2)\%$$
$$RMS\left(\frac{\Delta E}{E}\right) = (10.33 \pm 0.11)\%$$

Mean energy deviation (plus case)

$$\left\langle \frac{\Delta E}{E} \right\rangle = (+15.9 \pm 1.8)\%$$
$$RMS\left(\frac{\Delta E}{E}\right) = (10.80 \pm 0.12)\%$$

Occurrence of such "worst cases" rather improbable (0.9% for 3-fold

event,
$$p_{wc} \simeq \left(\frac{1}{6}\right)^N$$
 for N-fold event)



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Conclusions

- Zenith angle dependency: Official parameters approved, statistical uncertainties improved by factor 2
- Energy estimation stable, deviations due to updated fluctuation parameters negligible
- Signal strength dependent signal fluctuations: All methods lead to compatible results
- Best model: Analytical model with threshold prediction (includes data points <10 VEM)</p>



Backup slides

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Correction of threshold effect

- Threshold clipping (S<10 VEM): correction either via</p>
 - Toy MC
 - correction function
- Toy MC:
 - generate simulated signal spectrum
 - take out signal of sim spectrum two fluctuated signal values
 - (Gaussian distribution with $\sigma = p_{\sigma}\sqrt{S}$)
 - create relative signal fluctuation plots with and without 3 VEM threshold cut
 - For each bin: correction factor
- Correction factor: obtained from threshold prediction

$$R(\overline{S}) = \overline{P}(\overline{S}, p_{\sigma})^{-2}$$



Dependency on the distance to the shower axis

Low distance to shower axis: additional difference of number of particles:

$$\sigma^2 = \left(p_{\sigma} \sqrt{S} \right)^2 + \left(p_{\sigma} \Delta S_{LDF} \right)^2$$

 ΔS_{LDF} from NKG-like LDF: $\Delta S_{LDF} = \frac{\partial S_{LDF}(r_c)}{\partial r_c} \Delta r_c$

$$p_{\sigma}(r_{c}) = p_{\sigma,0} \sqrt{1 + S_{0} \left(\frac{\partial f(r_{c})}{\partial r_{c}}\right)^{2} f(r_{c})^{\beta-2}} \quad \text{with } f(r_{c}) = \frac{r_{c}}{1000 \,\mathrm{m}} \frac{r_{c} + 700 \,\mathrm{m}}{1700 \,\mathrm{m}}$$

• Fit results: $p_{\sigma,0} = 0.925 \pm 0.009 \quad \beta = -1.9 \pm 0.9 \quad S_0 = (210 \pm 500) \text{ VEM}$



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Is $\Delta \mathbf{r}_{c}$ isotropic?

